# 3RW44 for high-feature applications

### More information

# Application examples for normal starting (Class 10)

Normal starting Class 10 (up to 20 s with 350 % In motor),

The soft starter rating can be selected	to be as high as the	e rating of the motor	used			
Application	Conveyor belt	Roller conveyor	Compressor	Small fan	Pump	Hydraulic pump
Starting parameters						
Voltage ramp and current limiting     Starting voltage %     Starting time s     Current limit value	70 10 Deactivated	60 10 Deactivated	50 10 4 × <i>I</i> <sub>M</sub>	30 10 4 × <i>I</i> <sub>M</sub>	30 10 Deactivated	30 10 Deactivated
Torque ramp     Starting torque     End torque     Starting time     Breakaway pulse	60 150 10	50 150 10 Deactivated (0 ms)	40 150 10	20 150 10 Deactivated (0 ms)	10 150 10 Deactivated (0 ms)	10 150 10
Ramp-down mode	Smooth ramp-down	Smooth ramp-down	Free ramp-down	Free ramp-down	Pump ramp-down	Free ramp-down

#### Application examples for heavy starting (Class 20)

*Heavy starting Class 20* (up to 40 s with 350 %  $I_{n \text{ motor}}$ ), The soft starter has to be selected one rating class higher than the motor used

Application		Stirrer	Centrifuge	Milling machine			
Starting parameters							
<ul> <li>Voltage ramp and current limiting</li> <li>Starting voltage</li> <li>Starting time</li> <li>Current limit value</li> </ul>	% S	30 30 4 × I <sub>M</sub>	30 30 4 × I <sub>M</sub>	30 30 4 × I <sub>M</sub>			
<ul> <li>Torque ramp</li> <li>Starting torque</li> <li>End torque</li> <li>Starting time</li> </ul>		30 150 30	30 150 30	30 150 30			
<ul> <li>Breakaway pulse</li> </ul>		Deactivated (0 ms)	Deactivated (0 ms)	Deactivated (0 ms)			
Ramp-down mode		Free ramp-down	Free ramp-down	Free ramp-down or DC braking			

# Application examples for very heavy starting (Class 30)

Very heavy starting Class 30 (up to 60 s with 350 % In motor),

The soft starter has to be selected two rating classes higher than the motor used							
Application		Large fan Mill		Breaker	Circular saw/bandsaw		
Starting parameters							
<ul> <li>Voltage ramp and current limiting</li> <li>Starting voltage</li> <li>Starting time</li> <li>Current limit value</li> </ul>	% S	30 60 4 × I <sub>M</sub>	50 60 4 × I <sub>M</sub>	50 60 4 × I <sub>M</sub>	30 60 4 × I <sub>M</sub>		
<ul> <li>Torque ramp</li> <li>Starting torque</li> <li>End torque</li> <li>Starting time</li> </ul>		20 150 60	50 150 60	50 150 60	20 150 60		
<ul> <li>Breakaway pulse</li> </ul>		Deactivated (0 ms)	80 %, 300 ms	80 %, 300 ms	Deactivated (0 ms)		
Ramp-down mode		Free ramp-down	Free ramp-down	Free ramp-down	Free ramp-down		

<u>Note:</u> These tables present sample set values and device sizes. They are intended only for the purposes of information and are not binding. The set values depend on the application in question and must be optimized during commissioning. The soft starter dimensions should be checked where necessary with the Win-Soft Starter software or with the help of Technical Assistance.

for high-feature applications

3RW44

# Circuit concept

The SIRIUS 3RW44 soft starters can be operated in two different types of circuit.

Inline circuit

The controls for isolating and protecting the motor are simply connected in series with the soft starter. The motor is connected to the soft starter with three cables.

Inside-delta circuit

The wiring is similar to that of wye-delta starters. The phases of the soft starter are connected in series with the individual motor windings. The soft starter then only has to carry the phase current, amounting to about 58 % of the rated motor current (conductor current).

# Comparison of the types of circuit



#### Inline circuit:

Rated current  $I_{\rm e}$  corresponds to the rated motor current  $I_{\rm n}$ , 3 cables to the motor



Inside-delta circuit:

Rated current  $I_{\rm e}$  corresponds to approx. 58 % of the rated motor current  $I_{\rm n}$ , 6 cables to the motor (as with wye-delta starters)

#### Which circuit?

Using the inline circuit involves the lowest wiring outlay. If the soft starter to motor connections are long, this contact sequence is preferable.

With the inside-delta circuit there is double the wiring complexity but a smaller size of device can be used at the same rating.

Thanks to the choice of operating mode select between the inline circuit and inside-delta circuit, it is always possible to select the most favorable solution.

The braking function is possible only in the inline circuit.

#### Configuration

The 3RW44 solid-state soft starters are designed for normal starting. In case of heavy starting or increased starting frequency, a larger device must be selected.

For long starting times it is recommended to have a PTC thermistor detector in the motor. This also applies for the ramp-down modes smooth ramp-down, pump ramp-down and DC braking, because during the ramp-down time in these modes, an additional current loading applies in contrast to free ramp-down.

In the motor feeder between the SIRIUS 3RW soft starter and the motor, no capacitive elements are permitted (e.g. no reactive-power compensation equipment). In addition, neither static systems for reactive-power compensation nor dynamic PFC (Power Factor Correction) must be operated in parallel during starting and ramp-down of the soft starter. This is important to prevent faults arising on the compensation equipment and/or the soft starter.

All elements of the main circuit (such as fuses and controls) should be dimensioned for direct starting, following the local short-circuit conditions. Fuses, controls and overload relays must be ordered separately.

The harmonic component load for starting currents must be taken into consideration for the selection of motor starter protectors (selection of release).

#### Note:

When induction motors are switched on, voltage drops occur as a rule on starters of all types (direct starters, wye-delta starters, soft starters). The infeed transformer must always be dimensioned such that the voltage dip when starting the motor remains within the permissible tolerance. If the infeed transformer is dimensioned with only a small margin, it is best for the control voltage to be supplied from a separate circuit (independently of the main voltage) in order to avoid the potential switching off of the soft starter.

#### Device interface, PROFIBUS DP communications module, Soft Starter ES parameterizing and operating software

The 3RW44 solid-state soft starters have a PC interface for communicating with the Soft Starter ES 2006 Smart software or for connecting the external display and operator module. If the optional PROFIBUS communications module is used, the 3RW44 soft starter can be integrated in the PROFIBUS network and communicate using the GSD file or Soft Starter ES 2006 Professional software.

### Manual for SIRIUS 3RW44

Besides containing all important information on configuring, commissioning and servicing, the manual also contains example circuits and the technical specifications for all devices.

#### Win-Soft Starter selection and simulation program

With this software, you can simulate and select all Siemens soft starters, taking into account various parameters such as mains properties, motor and load data, and special application requirements.

The software is a valuable tool, which makes complicated, lengthy manual calculations for determining the required soft starters superfluous.

You can order the CD-ROM under the following order number: Order No.: E20001-D1020-P302-V2-7400.

More information can be found on the Internet at http://www.siemens.com/softstarter

# **3RW Soft Starters**

# 3RW44 for high-feature applications

#### SIRIUS soft starter training course (SD-SIRIUSO)

Siemens offers a 2-day training course on the SIRIUS solid-state soft starters to keep customers and own personnel up-to-date on configuring, commissioning and servicing issues.

Please direct enquiries and applications to:

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